CSE 392/CS 395T/M 397C: Matrix and Tensor Algorithms for Data

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Lecture 14: Stochastic Trace Estimation



1 Implicit trace estimation

2 Stochastic trace estimation



Matrix Trace

• Given a matrix $\mathbf{A} \in \mathbb{R}^{d \times d}$ our goal is to compute the trace:

$$\operatorname{Tr}(\boldsymbol{A}) = \sum_{i=1}^{d} \boldsymbol{A}_{ii}.$$

• In terms of the eigenvalues, if $\mathbf{A} = \mathbf{U}\Lambda\mathbf{U}^{\top}$ with $\Lambda = \text{diag}[\lambda_1, \dots, \lambda_d]$, we know:

$$\operatorname{Tr}(\boldsymbol{A}) = \sum_{i=1}^d \lambda_i.$$

• In many situations, access to **A** available only implicitly through a *matrix-vector multiplication oracle*. Estimate the trace implicitly (also called matrix-free)?

Spectral Sums

Given a symmetric positive semidefinite (PSD) matrix $\boldsymbol{A} \in \mathbb{R}^{d \times d}$ with eigen-decomposition $\boldsymbol{A} = \boldsymbol{U} \Lambda \boldsymbol{U}^T$ and eigenvalues $\{\lambda_i\}_{i=1}^d$, and desired function $f(\cdot)$, compute the trace of the matrix function $f(\boldsymbol{A}) = \boldsymbol{U} f(\Lambda) \boldsymbol{U}^\top$, i.e.,

$$\operatorname{Tr}(f(\boldsymbol{A})) = \sum_{i=1}^{u} f(\lambda_i).$$

- Popular examples: log-determinant $(\log(x))$, numerical rank (step function), spectral density $\delta(x \lambda_i)$, Schatten *p*-norms $(x^{p/2})$, von Neumann Entropy $(x \log(x))$, Estrada index $(\exp(x))$, trace of matrix inverse $(\frac{1}{x})$.
- *Applications:* machine learning, graph signal processing, quantum algorithms, scientific computing, statistics, computational biology and physics.
- Naive approaches : Eigenvalue decomposition, Cholesky Decomposition, singular value decomposition (SVD). Cost: $O(d^3)$ or [Theory: $O(d^{\omega})$ and $\omega = 2.373$].

Implicit trace estimation

- Access to **A** implicitly through a *matrix-vector multiplication oracle*.
- Typically useful when A is not stored explicitly, but we have an efficient algorithm for multiplying A by a vector.
- Matrix-vector products (Matvecs) cost $O(nnz(\mathbf{A}))$.
- *Examples:* Hessians in optimization, matrix functions as polynomials, structured matrices, etc.



How many matvecs Ax_1, \ldots, Ax_m are needed to estimate the trace?

A naive approach

- Set $\boldsymbol{x}_l = \boldsymbol{e}_l$ for $l = 1, \ldots, d$.
- Return $\operatorname{Tr}(\boldsymbol{A}) = \sum_{l=1}^{d} \boldsymbol{x}_{l}^{\top} \boldsymbol{A} \boldsymbol{x}_{l}.$
- Total computational cost $O(nnz(\mathbf{A})d)$.



Exact solution, but required d matvecs. Can we approximately estimate the trace with $\ll d$ matvecs?

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Stochastic Trace Estimation

Hutchinson's stochastic trace estimator

• Hutchinson [Hutchinson, 1990] proposed a method for implicit matrix trace estimation:

$$\operatorname{Tr}(A) \approx \frac{1}{m} \sum_{l=1}^{m} \boldsymbol{x}_{l}^{\top} A \boldsymbol{x}_{l}, \qquad (1)$$

where $\boldsymbol{x}_l, l = 1, \dots, m$, are random vectors with i.i.d. random $\{+1, -1\}$ entries.

- Randomized method: Simple, powerful, and widely used method for trace estimation.
- Theoretical analyses were presented in [Avron, Toledo 2011], [Roosta, Ascher 2015].



Stochastic trace estimator

Theorem

Let \mathbf{A} be an $d \times d$ symmetric positive semidefinite (PSD) matrix and $\mathbf{x}_l, l = 1, \ldots, m$ be random starting vectors with Radamacher distribution. Then, for $\tilde{\mathrm{Tr}}_m(\mathbf{A}) = \frac{1}{m} \sum_{l=1}^m \mathbf{x}_l^\top \mathbf{A} \mathbf{x}_l$, with $m = O\left(\frac{\log(1/\eta)}{\epsilon^2}\right)$, we have

$$\Pr\left[\left|\tilde{\operatorname{Tr}}_{m}(\boldsymbol{A}) - \operatorname{Tr}(\boldsymbol{A})\right| \leq \epsilon |\operatorname{Tr}(\boldsymbol{A})|\right] \geq 1 - \eta.$$

Radamacher distribution: vectors with $\{\pm 1\}$ entries with equal probabilities.



Expected Value Analysis

Hutchinson's Estimator:

- Draw $\boldsymbol{x}_l, l = 1, \dots, m$, vectors with i.i.d. random $\{+1, -1\}$ entries.
- Return $\tilde{\mathrm{Tr}}_m(\mathbf{A}) = \frac{1}{m} \sum_{l=1}^m \mathbf{x}_l^\top \mathbf{A} \mathbf{x}_l$ as approximation to $\mathrm{Tr}(\mathbf{A})$.

Expected value analysis:

For a single random ± 1 vector \boldsymbol{x} , we have

$$\mathbb{E}[\tilde{\mathrm{Tr}}_m(\boldsymbol{A})] = \mathbb{E}[\boldsymbol{x}_l^{\top} \boldsymbol{A} \boldsymbol{x}_l] = \mathbb{E}\sum_{i=1}^d \sum_{j=1}^d x_i x_j \boldsymbol{A}_{ij} = \sum_{i=1}^d \sum_{j=1}^d \mathbb{E}[x_i x_j \boldsymbol{A}_{ij}] = \sum_{i=1}^d \boldsymbol{A}_{ii}$$

So the estimator is correct in expectation:

$$\mathbb{E}[\tilde{\mathrm{Tr}}_m(\boldsymbol{A})] = \mathrm{Tr}(\boldsymbol{A}).$$

Variance Analysis

Hutchinson's Estimator:

- Draw $x_l, l = 1, ..., m$, vectors with i.i.d. random $\{+1, -1\}$ entries.
- Return $\tilde{\mathrm{Tr}}_m(\boldsymbol{A}) = \frac{1}{m} \sum_{l=1}^m \boldsymbol{x}_l^\top \boldsymbol{A} \boldsymbol{x}_l$ as approximation to $\mathrm{Tr}(\boldsymbol{A})$.

Variance analysis:

$$\begin{aligned} \operatorname{Var}[\tilde{\operatorname{Tr}}_{m}(\boldsymbol{A})] &= \frac{1}{m} \operatorname{Var}[\boldsymbol{x}_{l}^{\top} \boldsymbol{A} \boldsymbol{x}_{l}] = \frac{1}{m} \left[\mathbb{E}[(\boldsymbol{x}_{l}^{\top} \boldsymbol{A} \boldsymbol{x}_{l})^{2}] - \operatorname{Tr}(\boldsymbol{A})^{2} \right] \\ \mathbb{E}[(\boldsymbol{x}_{l}^{\top} \boldsymbol{A} \boldsymbol{x}_{l})^{2}] &= \mathbb{E} \left[(\sum_{i,j} x_{i} x_{j} \boldsymbol{A}_{ij}) (\sum_{i',j'} x_{i'} x_{j'} \boldsymbol{A}_{i'j'}) \right] \\ &= 2 \sum_{i \neq j} \boldsymbol{A}_{ij}^{2} + \sum_{i \neq j} \boldsymbol{A}_{ii} \boldsymbol{A}_{jj} + \sum_{i} \boldsymbol{A}_{ii}^{2} \end{aligned}$$

We used that $x_i x_j$ and $x_{i'} x_{j'}$ are pairwise independent. Therefore,

$$\operatorname{Var}[\tilde{\operatorname{Tr}}_m(\boldsymbol{A})] = \frac{2}{m} \sum_{i \neq j} \boldsymbol{A}_{ij}^2 \leq \frac{2}{m} \|\boldsymbol{A}\|_F^2.$$

Analysis

Chebyshev's inequality : $\Pr(|X - \mathbb{E}[X]| \ge \tau) \le \frac{\operatorname{Var}(X)}{\tau^2}$.

We have $\mathbb{E}[\tilde{\mathrm{Tr}}_m(\mathbf{A})] = \mathrm{Tr}(\mathbf{A})$ and $\mathrm{Var}[\tilde{\mathrm{Tr}}_m(\mathbf{A})] \leq \frac{2}{m} \|\mathbf{A}\|_F^2$. Choosing $\tau = \epsilon \cdot \mathrm{Tr}(\mathbf{A})$:

$$\begin{aligned} \Pr(\left|\tilde{\mathrm{Tr}}_{m}(\boldsymbol{A}) - \mathrm{Tr}(\boldsymbol{A})\right| \geq \epsilon \cdot \mathrm{Tr}(\boldsymbol{A})\right) &\leq \frac{\mathrm{Var}(\tilde{\mathrm{Tr}}_{m}(\boldsymbol{A}))}{(\epsilon \cdot \mathrm{Tr}(\boldsymbol{A}))^{2}} \\ &\leq \frac{2}{m} \frac{\|\boldsymbol{A}\|_{F}^{2}}{(\epsilon \cdot \mathrm{Tr}(\boldsymbol{A}))^{2}} = \frac{2}{m\epsilon^{2}}. \end{aligned}$$

For probability η , we can select $m \geq \frac{2}{\eta \epsilon^2}$.

Can improve this to $m = O\left(\frac{\log(1/\eta)}{\epsilon^2}\right)$, using Hanson-Wright inequality.

Improved Analysis

Hanson-Wright inequality [Hanson & Wright, 1971] : Given a symmetric matrix A and random vector x with i.i.d sub-Gaussian entries, with constant sub-Gaussian parameter C, we have for $t \ge 0$:

$$\Pr\left(\left|\boldsymbol{x}^{\top}\boldsymbol{A}\boldsymbol{x} - \mathbb{E}[\boldsymbol{x}^{\top}\boldsymbol{A}\boldsymbol{x}]\right| \geq t\right) \leq 2\exp\left(-c \cdot \min\left(\frac{t^2}{\|\boldsymbol{A}\|_F^2}, \frac{t}{\|\boldsymbol{A}\|_2}\right)\right),$$

for some universal constant c > 0 that only depending on C.

Improved Analysis

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for some universal constant c > 0 that only depending on C.

Markov's inequality :

$$\Pr(|X - \mathbb{E}[X]| \ge \tau) \le \frac{\mathbb{E}[X^q]}{\tau^q}.$$

Choose $\tau = (2\epsilon - \epsilon^2) \cdot \text{Tr}(\mathbf{A})$ and $q = \log(1/\eta)$, then with some work we get the theorem with $m = O\left(\frac{\log(1/\eta)}{\epsilon^2}\right)$. Alternatively, can also use the Markov's inequality (the exponential version) and some recent results, see [Roosta, Ascher 2015].

Further Reading:

- Randomized algorithms for estimating the trace of an implicit symmetric positive semi-definite matrix. by H. Avron and S. Toledo.
- Improved bounds on sample size for implicit matrix trace estimators by Roosta-Khorasani and Uri Ascher.

Exercise:

Would the proof using the Chebyshev inequality work if x_l's are drawn from i.i.d Gaussian distribution N(0, 1)? What are the expectation and the variance of the estimate? (Hint: Note that y_l = Ux_l are also Gaussian for unitary U. χ²-distribution.)

Hutch++

Hutch++ : Improved trace estimator

- Hutchinson's estimator is powerful, and gives a good rate of convergence. But requires $m = O(1/\epsilon^2)$ random vectors and matvecs.
- Recent results by Meyer et al., 2021, showed we can improve this to $m = O(1/\epsilon)$ matvecs.
- *Idea of Hutch++* Matrices might have decaying eigenvalues. Trace of a low rank approximation of the matrix is a good approximation to the matrix trace.
- Split the trace (spectrum) as sum of trace of top k eigenvalues and bottom n k eigenvalues.

$$\operatorname{Tr}(\boldsymbol{A}) = \operatorname{Tr}(\boldsymbol{A}_k) + \operatorname{Tr}(\boldsymbol{A} - \boldsymbol{A}_k).$$

Meyer, Raphael A., et al. "Hutch++: Optimal stochastic trace estimation." Symposium on Simplicity in Algorithms (SOSA). Society for Industrial and Applied Mathematics, 2021.

Hutch++



Explicitly estimate the top few eigenvalues of A. Use Hutchinson's for the rest.

- Find a good rank-k approximation \tilde{A}_k .
- Observe $\operatorname{Tr}(\mathbf{A}) = \operatorname{Tr}(\tilde{\mathbf{A}}_k) + \operatorname{Tr}(\mathbf{A} \tilde{\mathbf{A}}_k).$
- Compute $\operatorname{Tr}(\tilde{A}_k)$ exactly.
- Return Hutch++(\mathbf{A}) = Tr($\tilde{\mathbf{A}}_k$) + Tr_m($\mathbf{A} \tilde{\mathbf{A}}_k$)).
- If $k = m = O(1/\epsilon)$, then $|\operatorname{Hutch} + +(\boldsymbol{A}) \operatorname{Tr}(\boldsymbol{A})| \le \epsilon \operatorname{Tr}(\boldsymbol{A})$.

Good low rank approximation

Let A_k be the best rank-k approximation of A.

Lemma (Woo14)

Let $\mathbf{S} \in \mathbb{R}^{d \times m}$ have i.i.d. random entries from $\mathcal{N}(0,1)$, $\mathbf{Q} = orth(\mathbf{AS})$ and $\tilde{\mathbf{A}}_k = \mathbf{Q}\mathbf{Q}^T\mathbf{A}$. Then if $m = O(k + \log(1/\delta))$, with probability $1 - \delta$,

$$\|\boldsymbol{A} - \tilde{\boldsymbol{A}}_k\|_F \le 2\|\boldsymbol{A} - \boldsymbol{A}_k\|_F.$$

We can compute $\operatorname{Tr}(\tilde{A}_k)$ with 2m matvecs with A and O(mn) space:

$$\operatorname{Tr}(\tilde{\boldsymbol{A}}_k) = \operatorname{Tr}(\boldsymbol{Q}\boldsymbol{Q}^T\boldsymbol{A}) = \operatorname{Tr}(\boldsymbol{Q}^T(\boldsymbol{A}\boldsymbol{Q}))$$

Hutch++ Algorithm

- Input: Number of matvecs *m* and input matrix *A*.
- Sample $\boldsymbol{S} \in \mathbb{R}^{d \times m/3}$ and $\boldsymbol{G} \in \mathbb{R}^{d \times m/3}$ with i.i.d. entries from $\mathcal{N}(0, 1)$.
- Compute $\boldsymbol{Q} = \operatorname{orth}(\boldsymbol{AS})$.
- Return Hutch++(\boldsymbol{A}) = Tr($\boldsymbol{Q}^{T}(\boldsymbol{A}\boldsymbol{Q})$) + $\frac{3}{m}$ Tr($\boldsymbol{G}^{T}(I \boldsymbol{Q}\boldsymbol{Q}^{T})\boldsymbol{A}(I \boldsymbol{Q}\boldsymbol{Q}^{T})\boldsymbol{G}$).

We have the following result:

Lemma

Let $\mathbf{A} \in \mathbb{R}^{d \times d}$ be a PSD matrix and \mathbf{A}_k be its best rank-k approximation. Then,

$$\|\boldsymbol{A} - \boldsymbol{A}_k\|_F \le rac{1}{2\sqrt{k}}\operatorname{Tr}(\boldsymbol{A})$$

Hutch++ mean and variance

Theorem

Let $A \in \mathbb{R}^{d \times d}$ be a PSD matrix, for fixed k and m, construct $Q \in \mathbb{R}^{d \times m}$ as before. Let $Hutch++(A) = Tr(Q^T(AQ)) + Tr_m((I - QQ^T)A)$. Then,

$$\mathbb{E}[Hutch + +(\mathbf{A})] = \operatorname{Tr}(\mathbf{A})$$
$$\operatorname{Var}[Hutch + +(\mathbf{A})] \leq \frac{1}{km} \operatorname{Tr}^{2}(\mathbf{A})$$

For the mean, we have $\mathbb{E}[Hutch + +(\mathbf{A})] = \mathbb{E}[\operatorname{Tr}(\mathbf{Q}^T(\mathbf{A}\mathbf{Q}))] + \mathbb{E}[\mathbb{E}[\tilde{\operatorname{Tr}}_m((I - \mathbf{Q}\mathbf{Q}^T)\mathbf{A})|\mathbf{Q}]].$

For variance, we use the Conditional Variance Formula,

 $\operatorname{Var}[Hutch + +(\mathbf{A})] = \mathbb{E}[\operatorname{Var}[Hutch + +(\mathbf{A})|\mathbf{Q}]] + \operatorname{Var}[\mathbb{E}[Hutch + +(\mathbf{A})|\mathbf{Q}]].$

Can show $\operatorname{Var}[\mathbb{E}[Hutch + +(\mathbf{A})|\mathbf{Q}]] = 0.$

Exercise

Further Reading:

- Meyer, Raphael A., et al. "Hutch++: Optimal stochastic trace estimation." Symposium on Simplicity in Algorithms (SOSA). Society for Industrial and Applied Mathematics, 2021.
- https://ram900.com/hutchplusplus/

Hints for Problem 4 in HW2: Write $\|\boldsymbol{A} - \boldsymbol{A}_k\|_F$ and $\operatorname{Tr}(\boldsymbol{A})$ in terms of eigenvalues. Next, use the Holder's inequality $\|v\|_2^2 \leq \|v\|_1 \|v\|_{\infty}$. Note the function $\gamma \to \frac{\sqrt{a\gamma}}{b+\gamma}$ is maximized at $\gamma = b$, so $\frac{\sqrt{a\gamma}}{b+\gamma} \leq \frac{\sqrt{ab}}{2b}$. Choose appropriate a and b to bound the ratio $\frac{\|\boldsymbol{A} - \boldsymbol{A}_k\|_F}{\operatorname{Tr}(\boldsymbol{A})}$.

Matlab Demo